

# 17. SYSTEM OF NONLINEAR EQUATIONS

Problem statement: Solution of equations:  $f(x, y) = 0$   
 $g(x, y) = 0$

Symbolic solution: manipulation with expressions

Numeric solution: (i) separation of roots

(ii) iterative approximation of separate roots

## COMMANDS

SYMS  
 SOLVE  
 DOUBLE  
 EZPLOT  
 FUNCTION

### 17.1 Symbolic Solution

Characteristics:

1. Symbolic solution is not always possible
2. Substitution allows conversion to numerical solution

% Example 17.1: Symbolic solution of system of nonlinear equations

% Equation1:  $f(x,y)=x^2-2*x-y+0.5=0$

% Equation2:  $g(x,y)=x^2+4*y^2-4=0$

syms x y

R1=solve('x^2-2\*x-y+0.5=0','x^2+4\*y^2-4=0');

R1.x; R1.y;

X1=double(R1.x), Y1=double(R1.y)

% Visualization

ezplot('x^2-2\*x-y+0.5=0',[-1 3]); grid on

hold on; ezplot('x^2+4\*y^2-4=0');

plot(X1([1 4]),Y1([1 4]),'or'); hold off

title('SYSTEM OF NONLINEAR EQUATIONS')

### 17.2 Numeric Solution

Principle of the Newton method for the system of equations:

1. Expansion of multivariable functions into Taylor series is used
2. Principle is the same as in the one dimensional case

%%% Example 17.2: Solution of system of nonlinear equations

%%% Equation1:  $f(x,y)=x^2-2*x-y+0.5=0$

%%% Equation2:  $g(x,y)=x^2+4*y^2-4=0$

%%% for initial approximation P, accuracy eps and for

%%% maximum number of iterations M

P=[4 2]'; eps=1e-12; M=40; PG=P;

for k=2:M

DF=J(P); F=[-f(P); -g(P)];

DP=inv(DF)\*F;

P=P+DP; PG=[PG P];

if abs(sum(DP))<eps, break, end

end

xk=P(:,end);

plot(PG'); grid on; title('SOLUTION EVOLUTION')

%%%

function z=f(P)                      function z=g(P)

x=P(1); y=P(2);                    x=P(1); y=P(2);

z=x^2-2\*x-y+0.5;                    z=x^2+4\*y^2-4;

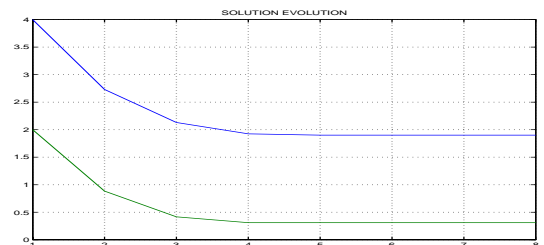
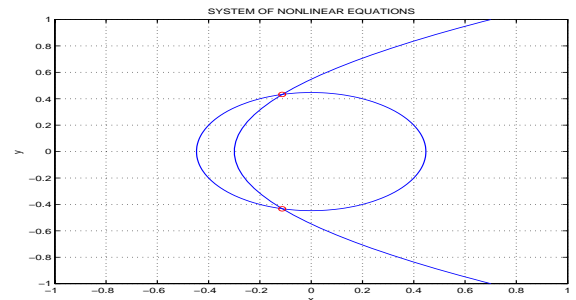
%%%

function W=J(P)

x=P(1); y=P(2);

W=[(2\*x-2) (-1);

(2\*x) (8\*y)];



## EXAMPLES 17

17.1 Evaluate symbolic solution of a selected system of nonlinear equations

17.2 Evaluate numeric solution of a selected system of nonlinear equations